

Investigating Effects of Insulin Estimation on Future Insulin Sensors' Design and Implication for AP Diabetes Management

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MOTIVATION & OBJECTIVE

- Incorporation of an insulin sensor may help to improve the performance of future artificial pancreas (AP) algorithms.
- Proof-of-concept evaluation can help to determine the potential benefit of using insulin level in a safety framework for hypoglycemia prevention for those with type 1 diabetes mellitus (T1DM).
- Identifying optimal insulin measurement intervals is needed for a feedback-based threshold suspend safety-layer.
- **Developing future insulin sensors could improve the safety of AP systems.**

METHODS

Kalman Filter EPIC Measurements

- A Kalman filter (KF) was designed as a state observer to estimate insulin concentration. Personalized KF-estimated plasma insulin concentration (EPIC) measurements aided a validated zone model predictive control (Zone-MPC) algorithm through a feedback-based threshold suspend safety layer [1].
- **Insulin delivery was suspended when:**
 - **CGM < 140 mg/dL AND**
 - **EPIC values > [fasting basal + 0.02 IU]**
- **EPIC measurements occurred at 5-, 30-, 60-, 120-, and 180-min intervals.**

Kalman Filter Sequence:

1. Prediction

Based on approximate insulin profile model

State Estimate \hat{x} :

$$\hat{x}_{k-1|k-1} = A_d \hat{x}_{k|k} + B_d u_k$$

Uncertainty P :

$$P_{k-1|k-1} = A_d P_{k|k} A_d^T + Q$$

Model matrix: A_d

Input matrix: B_d

Measurement matrix: C_d

2. Measurement/Update

Compare prediction to measurements

Kalman Gain K :

$$K_{k+1} = P_{k+1|k} C^T [C P_{k+1|k} C^T + R]^{-1}$$

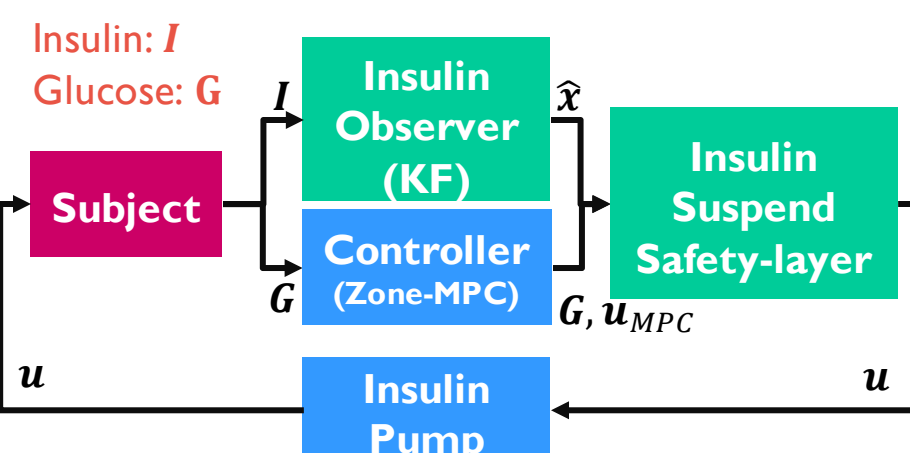
State Update \hat{x} :

$$\hat{x}_{k+1|k+1} = \hat{x}_{k+1|k} + K_{k+1} [y_{k+1} - C \hat{x}_{k+1|k}]$$

Uncertainty P :

$$P_{k+1|k+1} = [I - K_k C] P_{k+1|k}$$

Insulin Suspend Safety-Layer Feedback



METHODS CONTINUED

UVA/Padova T1DM Metabolic Simulator *In-silico* Protocol

The safety-layer was evaluated across **10 *in-silico* subjects** for a closed-loop **8-hour simulation** with a **single 50g-carbohydrate (CHO) announced meal** [2]. Three experiments were performed to introduce **challenging scenarios that might induce severe hypoglycemia**:



Scenario 1: Exercise

60-min exercise, induced via increased glucose uptake rates, 1-hr after an announced meal.



Scenario 2: Meal size & carbohydrate ratio (CR)

Meal size overestimation by 35% (e.g. 37 g-CHO with 50 g-CHO coverage) and CR underestimated by 25% (e.g. if CR was 1:10, the CR used in simulation would be 1:7.5, thus, more insulin is delivered).



Scenario 3: Baseline

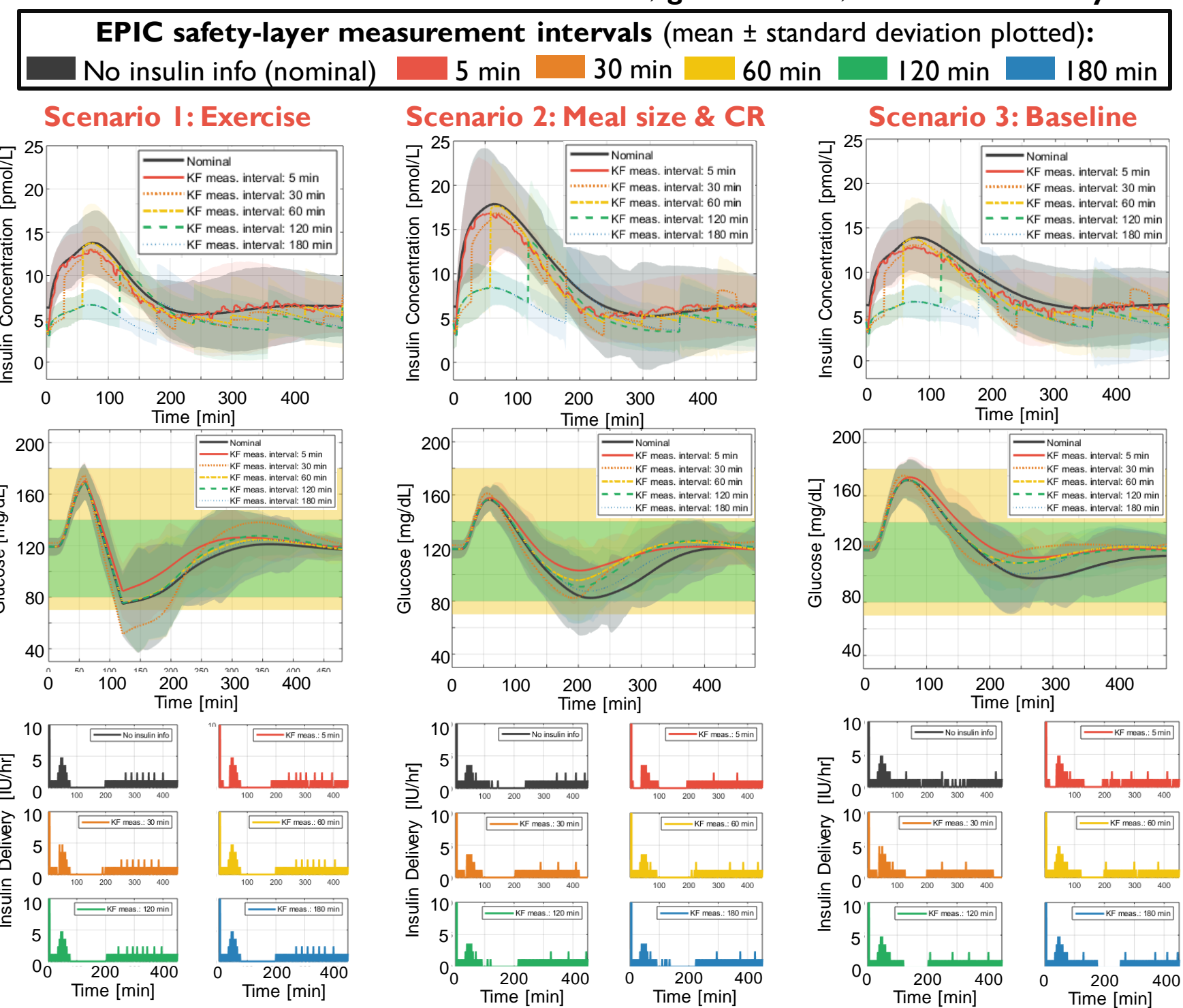
Announced meal (baseline)

RESULTS

- **Percent time below 70 mg/dL** (mean \pm standard deviation, *indicates p -value < 0.05)

	No EPIC	5-min	30-min	60-min	120-min	180-min
Scenario 1	8.1 \pm 9.1%	2.5 \pm 5.2%*	7.1 \pm 7.7%*	7.6 \pm 8.3%	7.6 \pm 8.3%	7.6 \pm 8.3%
Scenario 2	5.1 \pm 5.3%	0.0 \pm 0.0%*	0.0 \pm 0.0%*	0.9 \pm 2.8%*	2.1 \pm 4.6%*	3.2 \pm 5.4%
Scenario 3	0.7 \pm 2.2%	0.0 \pm 0.0%	0.0 \pm 0.0%	0.0 \pm 0.0%	0.0 \pm 0.0%	0.7 \pm 2.2%

- The plots below compare scenario results without insulin information to EPIC safety-layer KF measurement intervals for **insulin concentration, glucose level, and insulin delivery**.



CONCLUSION

- Incorporating insulin measurements reduced hypoglycemia during *in-silico* metabolic experiments
- Insulin measurements every 30 to 120 min yielded benefits similar to more frequent measurements, **supporting feasibility of intermittent determination of insulin levels**
- Incorporating insulin estimates may help to **improve performance of future AP algorithms by reducing severe hypoglycemia events during challenging scenarios** without significant rebound hyperglycemia.

[1] Gondhalekar, et al., Automatica 91, 2018

[2] Dalla Man, et al. J Diabetes Sci Technol 8(1), 2014

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